

PARABOLIC OBSTACLE-TYPE PROBLEMS

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Wittenberg, Germany, 12.12.11



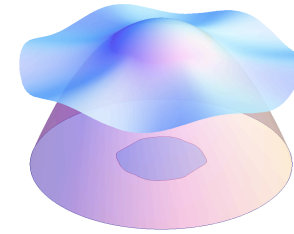
$$Hu = \Delta u - u_t = \chi_\Omega \text{ in } D$$

$$u = |\nabla u| = 0 \text{ in } D - \Omega$$

$$\|u\|_{\infty, D} \leq M$$

Obstacle Problem:

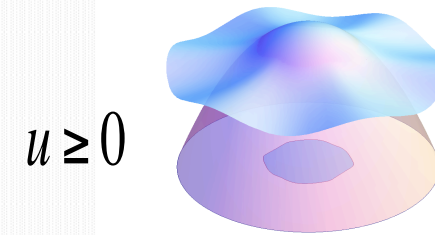
$$u \geq 0$$





$$\begin{aligned}Hu &= \Delta u - u_t = \chi_\Omega \text{ in } D \\ u &= |\nabla u| = 0 \text{ in } D - \Omega \\ \|u\|_{\infty, D} &\leq M\end{aligned}$$

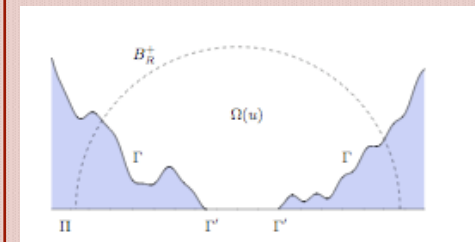
Obstacle Problem:



Contact Case

+

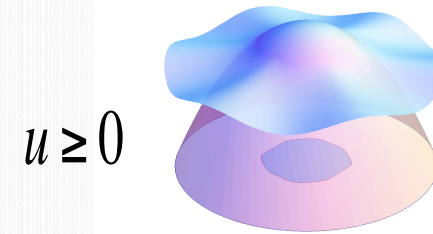
$$u = 0 \text{ on } \partial D$$





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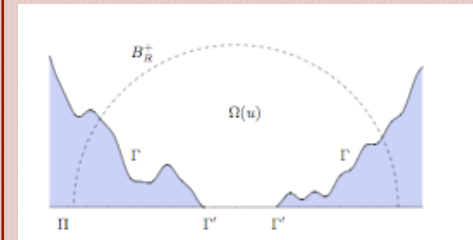
Obstacle Problem:



Contact Case

+

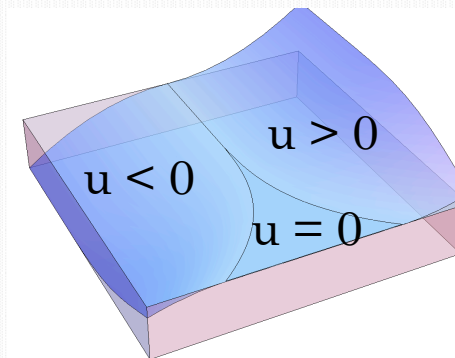
$$u = 0 \text{ on } \partial D$$



2-phase Problem:

$$Hu = \lambda_+ \chi_{\{u>0\}} - \lambda_- \chi_{\{u<0\}} \text{ in } D$$

$$\lambda_\pm > 0, \lambda_\pm \in \text{Lip}$$





1. How regular is \mathcal{U} ?

2. How regular is $\partial\Omega$?





1-PHASE PROBLEM

Optimal regularity of a solution

$$u \in C_x^{1,1} \cap C_t^{0,1}$$






1-PHASE PROBLEM

Optimal regularity of a solution

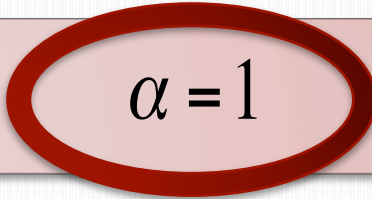
$$u \in C_x^{1,1} \cap C_t^{0,1}$$

- **Remark.**

Classical PDE-Theory gives that $|Hu|$ is bounded


$$u \in C_x^{1,\alpha} \cap C_t^{0,\alpha}$$

We want


$$\alpha = 1$$





WHY $\alpha = 1$ IS DESIRABLE?





WHY $\alpha = 1$ IS DESIRABLE?

$$u_r(x, t) = \frac{u(rx, r^2 t)}{r^2}$$

$$Hu_r = \chi_{\Omega_r}$$

If $\alpha = 1$ then u_r is bounded



We can go for a limit as $r \rightarrow 0$





WHY $\alpha = 1$ IS DESIRABLE?

$$u_r(x, t) = \frac{u(rx, r^2 t)}{r^2}$$

$$Hu_r = \chi_{\Omega_r}$$

$$u_r \rightarrow u_0$$

$$\Omega_r \rightarrow \Omega_0$$

If $\alpha = 1$ then u_r is bounded



We can go for a limit as $r \rightarrow 0$

Moreover,

$$Hu_0 = \chi_{\Omega_0} \text{ in } \mathbb{R}_+^{n+1}$$

$$u_0 = |Du_0| = 0 \text{ in } \mathbb{R}_+^{n+1} - \Omega_0$$

$$|u_0| \leq C(1 + |x|^2 + |t|)$$

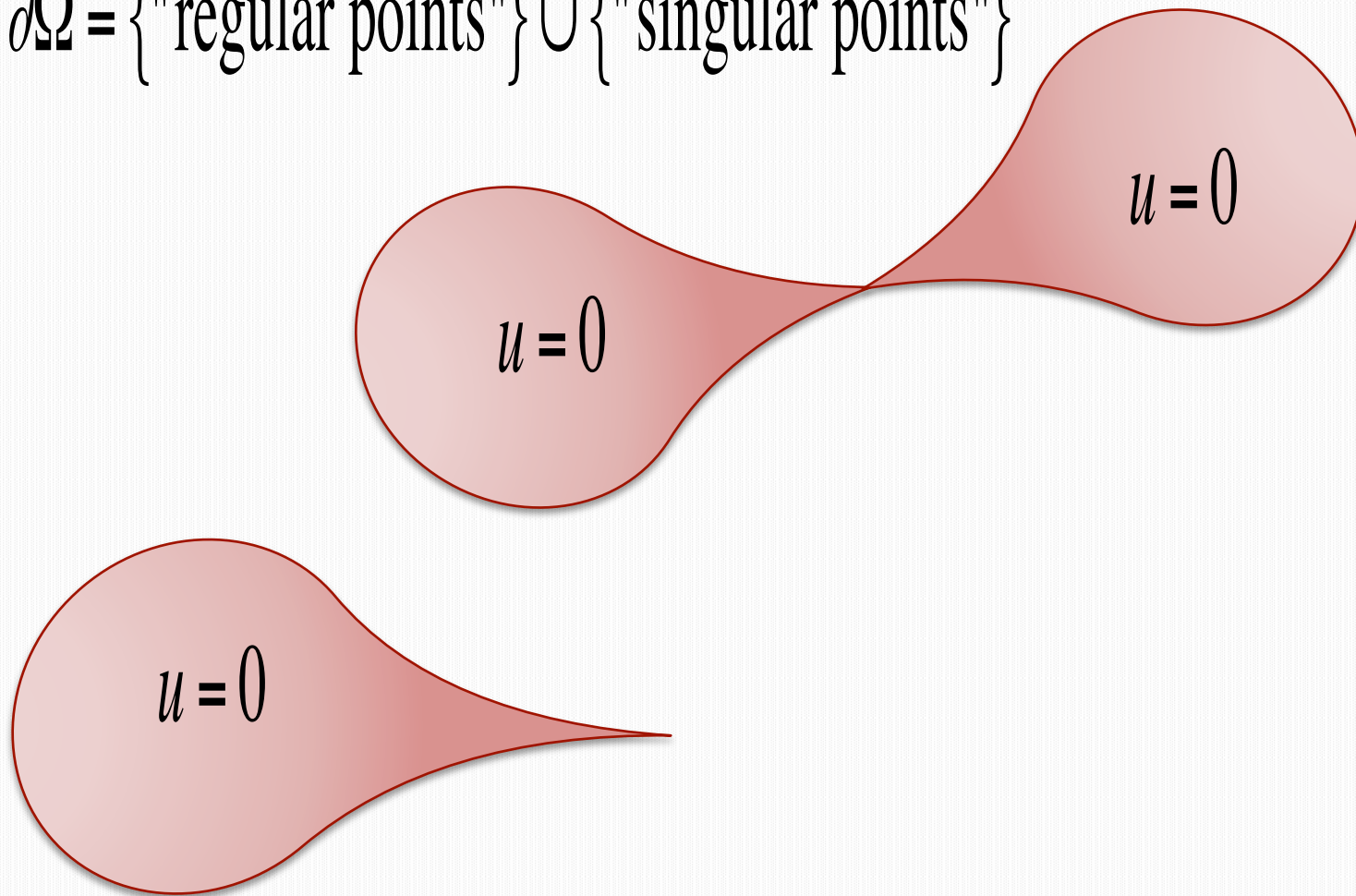




1-PHASE PROBLEM

Regularity of $\partial\Omega$

$$\partial\Omega = \{\text{"regular points"}\} \cup \{\text{"singular points"}\}$$





1-PHASE PROBLEM

Regularity of $\partial\Omega$





1-PHASE PROBLEM

Regularity of $\partial\Omega$

“thickness condition”

$$\begin{cases} Hu = \chi_{\Omega} \text{ in } Q \\ |u| = |\nabla u| = 0 \text{ in } Q - \Omega \end{cases}$$

No contact points !!!



$$\partial\Omega \cap R \in C^{1,\alpha}$$





1-PHASE PROBLEM

Regularity of $\partial\Omega$

“thickness condition”

$$\begin{cases} Hu = \chi_\Omega & \text{in } Q \\ |u| = |\nabla u| = 0 & \text{in } Q - \Omega \end{cases}$$

No contact points !!!



$$\partial\Omega \cap R \in C^{1,\alpha}$$

$$\begin{cases} Hu = \chi_\Omega & \text{in } Q^+ \\ u = |\nabla u| = 0 & \text{in } Q^+ - \Omega \\ u = 0 & \text{on } \{x_1 = 0\} \end{cases}$$

Contact points may exist!!!



$\partial\Omega \in \text{Lip}$
 $\partial\Omega \in C^{1,\alpha}$ at interior
points only!!!





2-PHASE PROBLEM

Optimal regularity of a solution

∇u is Lipschitz continuous w.r.t. space variables

∇u is Holder continuous with exponent $1/2$ w.r.t. time variable

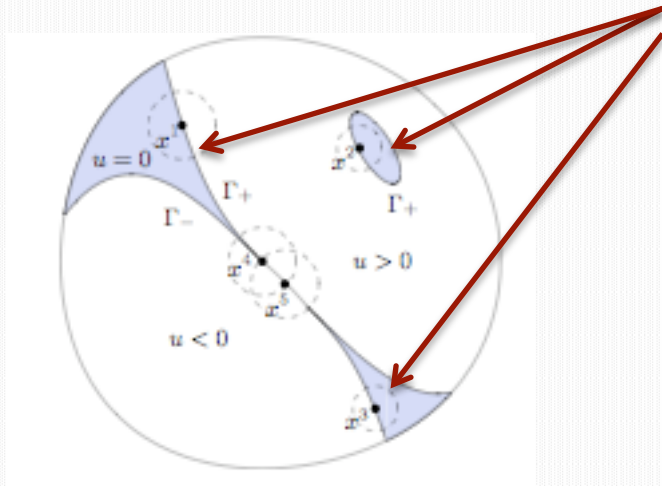




2-PHASE PROBLEM

Regularity of $\partial\Omega$

•1-phase points



$$\begin{aligned} &\partial\{u > 0\} \cap \{|\nabla u| = 0\} \\ &\partial\{u < 0\} \cap \{|\nabla u| = 0\} \end{aligned}$$

$$\partial\Omega \in C^{1,\alpha}$$

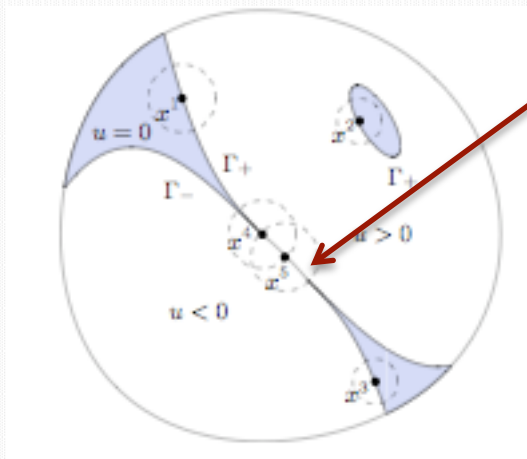




2-PHASE PROBLEM

Regularity of $\partial\Omega$

•2-phase nonbranch points



$$\{u = 0\} \cap \{|\nabla u| \neq 0\}$$

Implicit function
Theorem

$$\partial\Omega \in C^1$$

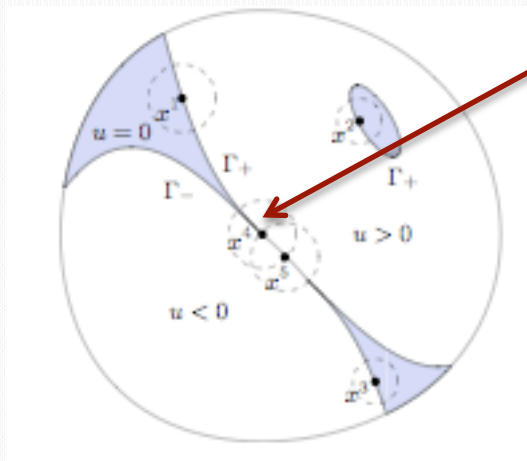




2-PHASE PROBLEM

Regularity of $\partial\Omega$

•2-phase branch points



near
 $\partial\{u > 0\} \cap \partial\{u < 0\} \cap \{|\nabla u| = 0\}$



$\partial\Omega$ is a union of two Lip - graphs,
which are continuously differentiable w.r.t space variables



FBP	Regularity of u	Regularity of the free boundary
$\begin{cases} Hu = \chi_{\Omega} & \text{in } Q \\ u = \nabla u = 0 & \text{in } \Omega^c \end{cases}$ <p>No contact points</p>	$u \in C_x^{1,1} \cap C_t^{0,1}$ <p>Optimal !</p>	$\partial\Omega = \{\text{"regular"}\} \cup \{\text{"singular"}\}$ <div style="border: 2px solid red; padding: 5px; margin: 10px auto; width: fit-content;"> <p>"thickness condition"</p> <p style="text-align: center;">↓</p> <p>$\partial\Omega \cap \mathbb{R} \in C^{1,\alpha}$</p> </div>
$\begin{cases} Hu = \chi_{\Omega} & \text{in } Q^+ \\ u = \nabla u = 0 & \text{in } \Omega^c \\ u = 0 & \text{on } \{x_1 = 0\} \end{cases}$ <p>Contact points may exist</p>	$u \in C_x^{1,1} \cap C_t^{0,1}$ <p>Optimal !</p>	$\partial\Omega \in \text{Lip}$ $\partial\Omega \in C^{1,\alpha} \text{ at interior points only!!!}$
$Hu = \lambda_+ \chi_{\{u>0\}} - \lambda_- \chi_{\{u<0\}}$	$\nabla u \in C_x^{0,1} \cap C_t^{0,1/2}$	$\partial\{u>0\} \cap \{\nabla u = 0\} \in C^{1,\alpha}$ $\{u = 0\} \cap \{\nabla u \neq 0\} \in C^1$ <div style="border: 2px solid red; padding: 5px; margin: 10px auto; width: fit-content;"> $\partial\{u>0\} \cap \partial\{u<0\} \cap \{\nabla u = 0\} \in \text{Lip}$ </div>



REFERENCES

1. L.A.Caffarelli, A.Petrosyan, H.Shahgholian, *J. Amer. Math. Soc.* (2004)
2. D.Apushkinskaya, N.Matevosyan, N.Uraltseva, *Indiana Univ. Math. J.* (2009)
3. H.Shahgholian, N.Uraltseva, G.Weiss, *Adv. Math.* (2009)





THANK YOU !!!

